

Antenna Mast AM 4.0

Technical Data

Antenna height automatic adjustable from 1.0 to 4.0 m (electrical)

Total mast height 4.6 m

Load capability 10 kg (when balanced) max. For long and heavy antennas a counter weight is required to balancing the load

Depending on the distance of the antenna centre of gravity

Material Plastic + reinforced fibreglass,

weatherproof

100 mm x 100 mm Mast cross-section Base L x W 1.3 m x 0.7 m

Positioning speed adjustable between 2 to 16 cm/sec.

Positioning accuracy +/- 1 cm

Electrical Polarisation 0°/90° (vert./hor.)

Positioning time 0°/90° approx. 3 sec.

Brushless DC motor 200 W Motor

Interference suppression: 20 dB under limits EN 55022 class B

2A Current consumption max.

Voltage

208-230 VAC, 50/60 Hz, single phase Discharge current

25mA per drive unit

(higher in the moment when powering on)

Fibre optic lines IEEE interface

Antenna support drive 2 toothed belts

Material of toothed belts Kevlar reinforced (non-metallic)

Bearings at mast slide Ball bearings

+10 °C...+35 °C Temperature range

Total weight 65 kg

Accessories Interface to MCU/NCD Controller

1.5 m power supply cable

Service manual

Brief description

Control cable

Remote control via

The Antenna Mast AM 4.0 is suitable in magnetic absorption chambers. The antenna mast, with the exception of the drive unit, is fabricated from plastic (PVC and reinforced fibreglass). Metal parts are located only in the base plate and the drive mechanism (max. 0.3 m above ground level).

Antenna Adapters for all commercially available antennas are available upon request. All antennas during polarisation rotate around their axis to eliminate any elevation errors.

The IEEE 488.2 (GPIB) bus provides an additional control option for all functions, when operated with the MCU or NCD Controller.



Antenna Mast AM 4.0



Information presented enclosed is subject to change as product enhancements are made regularly. Pictures included are for illustration purposes only and do not represent all possible configurations.